

## Linear eqn with variable coefficients

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## Section-1

## Introduction

A linear differential eqn of order  $n$  with variable coefficients is an eqn of the form,

$$a_0(x)y^{(n)} + a_1(x)y^{(n-1)} + \dots + a_n(x)y = b(x)$$

where  $a_0, a_1, \dots, a_n, b$  are complex valued functions on some real interval  $I$ . Points where  $a_0(x) = 0$  are called singular points and often the eqn requires special consideration at such points. Therefore in this case assume that  $a_0(x) \neq 0$  on  $I$ . By dividing by  $a_0$ , we can obtain an eqn of the same form, but with  $a_0$  replaced by the constant 1. Thus we consider the eqn.

$$y^{(n)} + a_1(x)y^{(n-1)} + \dots + a_n(x)y = b(x) \rightarrow \textcircled{1}$$

As in the case when  $a_1, \dots, a_n$  are constants we designate the left side of  $\textcircled{1}$  by  $L(y)$ . Thus

$$L(y) = y^{(n)} + a_1(x)y^{(n-1)} + \dots + a_n(x)y \rightarrow \textcircled{2}$$

And  $\textcircled{1}$  becomes simply  $L(y) = b(x)$ . If  $b(x) = 0 \forall x$  in  $I$  we say  $L(y) = 0$  is a homogeneous eqn. whereas if  $b(x) \neq 0$  for some  $x$  in  $I$ . The eqn  $L(y) = b(x)$  is called a non-homogeneous eqn.

We give a meaning to  $L$  itself as an operator which takes each function  $\phi$ , which has  $n$  derivatives on  $I$ , into the function  $L(\phi)$  on  $I$  whose value at  $x$  is given by

$$L(\phi)(x) = \phi^{(n)}(x) + a_1(x)\phi^{(n-1)}(x) + \dots + a_n(x)\phi(x)$$

Thus a soln of ① on  $I$  is a function  $\varphi$  on  $I$  which has  $n$  derivatives there and which satisfies  $L(\varphi) = b$ . (38)

In this chapter we assume that the complex valued functions  $a_1, a_2, \dots, a_n, b$  are continuous on some real interval  $I$  and  $L(y)$  will always denote the expression of ①

### Section-2

Initial value problem for the homogeneous eqn

Theorem: I Existence Theorem:

Let  $a_1, a_2, \dots, a_n$  be continuous function on an interval  $I$  containing the point  $x_0$ . If  $\alpha_1, \dots, \alpha_n$  are any  $n$  constants there exists a soln  $\varphi$  of

$$L(y) = y^{(n)} + a_1(x)y^{(n-1)} + \dots + a_n(x)y = 0$$

on  $I$  satisfying

$$\varphi(x_0) = \alpha_1, \varphi'(x_0) = \alpha_2, \dots, \varphi^{(n-1)}(x_0) = \alpha_n$$

Proof:

Let  $\varphi_1, \varphi_2, \dots, \varphi_n$  be any set of  $n$  linearly independent

Soln of

$$L(y) = y^{(n)} + a_1(x)y^{(n-1)} + \dots + a_n(x)y = 0$$

It will be s.t.  $\exists$  unique constants  $c_1, c_2, \dots, c_n$  such that

$$\varphi = c_1\varphi_1 + c_2\varphi_2 + \dots + c_n\varphi_n \text{ is a soln of } L(y) = 0$$

satisfying the condition given by ①

These constants would have to satisfy.

$$c_1\varphi_1(x_0) + c_2\varphi_2(x_0) + \dots + c_n\varphi_n(x_0) = \alpha_1$$

$$c_1\varphi_1'(x_0) + c_2\varphi_2'(x_0) + \dots + c_n\varphi_n'(x_0) = \alpha_2$$

⋮

$$c_1\varphi_1^{(n-1)}(x_0) + c_2\varphi_2^{(n-1)}(x_0) + \dots + c_n\varphi_n^{(n-1)}(x_0) = \alpha_n$$

This is a system of n linear equations for  $c_1, c_2, \dots, c_n$ .  
The displacement of the coefficient is just  $w(\phi_1, \phi_2, \dots, \phi_n)(x_0)$   
which is not zero.

∴ There is a unique set of constants  $c_1, c_2, \dots, c_n$   
satisfying

for this choice  $c_1, c_2, \dots, c_n$  the function

$$y = c_1 \phi_1 + c_2 \phi_2 + \dots + c_n \phi_n$$

Gives the desired soln.

Note:

There are two important things about the thm

- (i) The soln exists on the entire interval I, where  $a_1, a_2, \dots, a_n$  are continuous.
- (ii) Every initial value problem has a soln. Neither of these result may be true if the coefficient of  $y^{(n)}$  vanishes somewhere in I.

Example:

Consider the eqn  $xy' + y = 0$

$$\Rightarrow \frac{dy}{dx} = -\frac{y}{x}$$

$$\frac{dy}{y} + \frac{1}{x}y = 0$$

$$\int \frac{dy}{y} = -\int \frac{1}{x} dx$$

$$\ln y = -\ln x + C$$

$$y = \frac{c}{x}$$

where coefficients are continuous for all real x. This eqn and the initial condition  $y(1) = 1$ .

The soln  $\phi_1$

$$\phi_1(x) = \frac{1}{x}$$

But this soln exists only for  $0 < x < \infty$ . Also if  $\phi$  is any soln then,

$$x\phi(x) = c, \quad \text{where } c \text{ is constant.}$$

Thus only the trivial soln ( $c=0$ ) exists at the origin

⇒ The only IVP

$$xy' + y = 0, \quad y(0) = \alpha,$$

which has a soln is the one for which  $\alpha = 0$ .

Note:

$$\| \varphi(x) \|^2 = |\varphi(x)|^2 + |\varphi'(x)|^2 + \dots + |\varphi^{(n-1)}(x)|^2$$

Theorem: 2

Let  $b_1, b_2, \dots, b_n$  non negative constants such that

$x$  in  $I$   $|\varphi_j(x)| \leq b_j$  ( $j=1, 2, \dots, n$ ) and define  $k$  by

$k = 1 + b_1 + b_2 + \dots + b_n$ . If  $x_0$  is a point in  $I$  and  $\varphi$  is a

soln of  $L(\varphi) = 0$  on  $I$ . Then

$$\| \varphi(x_0) \| e^{-k|x-x_0|} \leq \| \varphi(x) \| \leq \| \varphi(x_0) \| e^{k|x-x_0|} \quad \text{for all } x \text{ in } I$$

Proof:

Since  $L(\varphi) = 0$

We have,

$$L(\varphi) = \varphi^{(n)}(x) + a_1(x) \varphi^{(n-1)}(x) + \dots + a_n(x) \varphi(x) = 0$$

$$\therefore \varphi^{(n)}(x) = -a_1(x) \varphi^{(n-1)}(x) - \dots - a_n(x) \varphi(x)$$

And therefore,

$$|\varphi^{(n)}(x)| = |-a_1(x) \varphi^{(n-1)}(x) - \dots - a_n(x) \varphi(x)|$$

$$\leq |a_1(x)| |\varphi^{(n-1)}(x)| + \dots + |a_n(x)| |\varphi(x)|$$

$$\leq |a_1(x)| |\varphi^{(n-1)}(x)| + \dots + |a_n(x)| |\varphi(x)|$$

$$|\varphi^{(n)}(x)| \leq b_1 |\varphi^{(n-1)}(x)| + \dots + b_n |\varphi(x)| \rightarrow \textcircled{1}$$

Let  $u(x) = \| \varphi(x) \|^2$

$$u(x) = |\varphi(x)|^2 + |\varphi'(x)|^2 + \dots + |\varphi^{(n-1)}(x)|^2$$

$$\Rightarrow u = \varphi \bar{\varphi} + \varphi' \bar{\varphi}' + \dots + \varphi^{(n-1)} \bar{\varphi}^{(n-1)}$$

Diff w.r.t  $x$  we get,

$$u' = \varphi' \bar{\varphi} + \varphi \bar{\varphi}' + \varphi'' \bar{\varphi}' + \varphi' \bar{\varphi}'' + \dots + \varphi^{(n)} \bar{\varphi}^{(n-1)} + \varphi^{(n-1)} \bar{\varphi}^{(n)}$$

$$|u'| \leq |\varphi'| |\bar{\varphi}| + |\varphi| |\bar{\varphi}'| + |\varphi''| |\bar{\varphi}'| + |\varphi' \bar{\varphi}''| + \dots + |\varphi^{(n)}| |\bar{\varphi}^{(n-1)}| + |\varphi^{(n-1)}| |\bar{\varphi}^{(n)}|$$

$$|u'| \leq 2|\varphi'| |\bar{\varphi}| + 2|\varphi| |\bar{\varphi}'| + \dots + 2|\varphi^{(n-1)}| |\bar{\varphi}^{(n)}| \rightarrow \textcircled{2}$$

Sub ① in ②

(4)

(5)

$$|u'| \leq 2|\phi||\phi'| + 2|\phi'|^2 + \dots + 2|\phi^{(n-1)}| [b_1|\phi^{(n-1)}(\alpha)| + \dots + b_n|\phi(\alpha)|]$$

$$|u'| \leq 2|\phi||\phi'| + 2|\phi'|^2 + \dots + 2b_1|\phi^{(n-1)}|^2 + 2b_2|\phi^{(n-1)}||\phi^{(n-2)}| + \dots + 2b_n|\phi^{(n-1)}||\phi|$$

using the inequality

$$2|b||c| \leq |b|^2 + |c|^2$$

We get,

$$\begin{aligned} |u'| &\leq [|\phi|^2 + |\phi'|^2] + [|\phi'|^2 + |\phi''|^2] + \dots + 2b_1|\phi^{(n-1)}|^2 + 2b_1|\phi^{(n-1)}||\phi^{(n-2)}| \\ &\quad + \dots + 2b_n|\phi^{(n-1)}||\phi| \\ &\leq [|\phi|^2 + |\phi'|^2] + [|\phi'|^2 + |\phi''|^2] + \dots + 2b_1|\phi^{(n-1)}|^2 + b_2[|\phi^{(n-1)}|^2 + |\phi^{(n-2)}|^2] \\ &\quad + \dots + b_n[|\phi^{(n-1)}|^2 + |\phi|^2] \\ &= (1+b_n)|\phi|^2 + (2+b_{n-1})|\phi'|^2 + \dots + (2+b_2)|\phi^{(n-2)}|^2 + \dots \\ &\quad + (1+2b_1+b_2+\dots+b_n)|\phi^{(n-1)}|^2 \end{aligned}$$

$$\begin{aligned} |u'| &= 2(1+b_1+b_2+\dots+b_n)|\phi|^2 + 2(1+b_1+b_2+\dots+b_n)|\phi'|^2 + \dots \\ &\quad + 2(1+b_1+b_2+\dots+b_n)|\phi^{(n-1)}|^2 \\ &= 2k|\phi|^2 + 2k|\phi'|^2 + \dots + 2k|\phi^{(n-1)}|^2 \\ &= 2k[|\phi|^2 + |\phi'|^2 + \dots + |\phi^{(n-1)}|^2] \end{aligned}$$

$$|u'| \leq 2ku$$

$$\Rightarrow -2ku \leq u' \leq 2ku$$

consider the right inequality which can be written as

$$u' - 2ku \leq 0$$

$$\Rightarrow \frac{-2ku}{e^{-2kx}} (u' - 2ku) \leq 0$$

$$\Rightarrow \frac{d}{dx} (e^{-2kx} u) \leq 0$$

If  $x > x_0$ , we integrate from  $x_0$  to  $x$  and get,

$$[e^{-2kx} u(x)]_{x_0}^x \leq 0$$

$$e^{-2kx} u(x) - e^{-2kx_0} u(x_0) \leq 0$$

$$e^{-2kx} u(x) \leq e^{-2kx_0} u(x_0)$$

$$u(x) \leq e^{2k(x-x_0)} u(x_0)$$

$$u(x) \leq u(x_0) e^{2k(x-x_0)}$$

$$\Rightarrow \| \varphi(x) \|^2 \leq \| \varphi(x_0) \|^2 e^{2k(x-x_0)}$$

$$\Rightarrow \| \varphi(x) \|^2 \leq \| \varphi(x_0) \|^2 e^{k|x-x_0|} \rightarrow \textcircled{3} \text{ if } x > x_0$$

Similarly The left inequality

$$\| \varphi(x_0) \|^2 e^{k|x-x_0|} \leq \| \varphi(x) \|^2 \rightarrow \textcircled{4} \text{ if } x < x_0$$

Combining  $\textcircled{3}$  and  $\textcircled{4}$  we get,

$$\| \varphi(x_0) \|^2 e^{-k|x-x_0|} \leq \| \varphi(x) \|^2 \leq \| \varphi(x_0) \|^2 e^{k|x-x_0|}$$

Hence The Theorem.

Remark:

If  $I$  is a closed bounded interval that is of the form  $a \leq x \leq b$  with  $a, b$  real and if the  $a_j$  are continuous then there always exist finite constants  $b_j$  such that,

$$|a_j(x)| \leq b_j \text{ on } I$$

Theorem: 3 uniqueness Theorem.

Let  $x_0$  be in  $I$  and let  $\alpha_1, \alpha_2, \dots, \alpha_n$  be any  $n$  constants. There is at most one soln  $\varphi$  of  $L(y) = 0$  on  $I$  satisfying

$$\varphi(x_0) = \alpha_1, \varphi'(x_0) = \alpha_2, \dots, \varphi^{(n-1)}(x_0) = \alpha_n$$

Proof:

Suppose,  $\varphi, \psi$  are two soln of  $L(y) = 0$  on  $I$  satisfying the conditions at  $x_0$ .

$$\text{Then } \theta = \varphi - \psi, \text{ satisfy } L[\theta] = 0$$

$$\text{and } \theta(x_0) = \theta'(x_0) = \dots = \theta^{(n-1)}(x_0) = 0$$

$$\text{Thus } \theta(x) = 0$$

From the inequality.

$$\| \theta(x_0) \| e^{-k|x-x_0|} \leq \| \varphi(x) \| \leq \| \theta(x_0) \| e^{k|x-x_0|}$$

We get,

$$\| \theta(x) \| = 0, \quad \forall x \text{ in } I$$

$$\text{(i) } \theta(x) = 0, \quad \forall x \text{ in } I$$

$$\Rightarrow \varphi = \gamma$$

Note:

$q_1(x) = x$  is not bounded on  $0 \leq x < \infty$  and  $q_1(x) = 1/x$

is not bounded on  $0 < x \leq 1$

### Section-3

Solns of the homogeneous equation.

If  $\varphi_1, \varphi_2, \dots, \varphi_m$  are any  $m$  solns of the  $n^{\text{th}}$  order eqn  $L(y) = 0$  on an interval  $I$  and  $c_1, c_2, \dots, c_m$  are any  $m$  constants then.

$$L(c_1\varphi_1 + c_2\varphi_2 + \dots + c_m\varphi_m) = c_1L(\varphi_1) + \dots + c_mL(\varphi_m)$$

$\Rightarrow c_1\varphi_1 + c_2\varphi_2 + \dots + c_m\varphi_m$  is also a soln.

Any linear combination of solns is again a soln. The trivial soln is the function which is identically zero on  $I$ .

#### Theorem 4

There exist  $n$  linearly independent solns of  $L(y) = 0$

on  $I$

Proof:

Let  $x_0$  be a point in  $I$ .

by Thm 1 There is a soln  $\varphi_1$  of  $L(y) = 0$  satisfying

$$\varphi_1(x_0) = 1, \quad \varphi_1'(x_0) = 0, \dots, \varphi_1^{(n-1)}(x_0) = 0$$

In general for each  $i = 1, 2, \dots, n$  There is a soln  $\varphi_i$  satisfying

$$\varphi_i^{(i-1)}(x_0) = 1, \quad \varphi_i^{(j-1)}(x_0) = 0 \quad \text{if } j \neq i \rightarrow \text{Q.E.D.}$$

The solns  $\phi_1, \phi_2, \dots, \phi_n$  are linearly independent on  $J$ .

Suppose there are constants  $c_1, c_2, \dots, c_n$  such that,

$$c_1 \phi_1(x) + c_2 \phi_2(x) + \dots + c_n \phi_n(x) = 0 \rightarrow \textcircled{2}$$

Diff w.r.t  $x$  we get,

$$c_1 \phi_1'(x) + c_2 \phi_2'(x) + \dots + c_n \phi_n'(x) = 0$$

$$c_1 \phi_1''(x) + c_2 \phi_2''(x) + \dots + c_n \phi_n''(x) = 0$$

$$\vdots$$

$$c_1 \phi_1^{(n-1)}(x) + c_2 \phi_2^{(n-1)}(x) + \dots + c_n \phi_n^{(n-1)}(x) = 0$$

$\rightarrow \textcircled{3}$

In particular eqn  $\textcircled{2}$  and  $\textcircled{3}$  must hold at  $x_0$ . Putting  $x=x_0$  and using  $\textcircled{1}$

we get,

$$c_1(1) + 0 + \dots + 0 = 0$$

$$\therefore c_1 = 0$$

Putting  $x=x_0$  in eqn  $\textcircled{3}$

we obtain,

$$c_2 = c_3 = \dots = c_n = 0$$

Thus the solns  $\phi_1, \phi_2, \dots, \phi_n$  are linearly independent.

Theorem: 5

Let  $\phi_1, \phi_2, \dots, \phi_n$  be the  $n$  solns of  $L(y) = 0$  on  $I$  satisfying  $\phi_i^{(i-1)}(x_0) = 1, \phi_j^{(j-1)}(x_0) = 0$  if  $i \neq j$ . If  $\phi$  is

any soln of  $L(y) = 0$  on  $I$ , there are  $n$  constants  $c_1, c_2, \dots, c_n$

such that  $\phi = c_1 \phi_1 + c_2 \phi_2 + \dots + c_n \phi_n$

Proof:

$$\text{Let } \phi(x_0) = d_1, \phi'(x_0) = d_2, \dots, \phi^{(n-1)}(x_0) = d_n$$

consider the function,

$$\psi = d_1 \phi_1 + d_2 \phi_2 + \dots + d_n \phi_n$$

It is a soln of  $L(y) = 0$

$$\therefore \psi(x_0) = d_1 \phi_1(x_0) + d_2 \phi_2(x_0) + \dots + d_n \phi_n(x_0) = d_1 \rightarrow \textcircled{*}$$

$$\text{Since } \phi_1(x_0) = 1, \phi_2(x_0) = 0, \dots, \phi_n(x_0) = 0$$

$(*) \Rightarrow \varphi(x_0) = \alpha_1, \varphi'(x_0) = \alpha_2, \dots, \varphi^{(n-1)}(x_0) = \alpha_n$

Thus  $\varphi$  is a soln of  $L(y) = 0$ , satisfying the same initial conditions at  $x_0$  as  $\varphi$ .

By uniqueness thm, we must have,

$\varphi = \varphi$  i.e)  $\varphi = \alpha_1 \varphi_1 + \alpha_2 \varphi_2 + \dots + \alpha_n \varphi_n$

We have proved the thm with the constants

$C_1 = \alpha_1, C_2 = \alpha_2, \dots, C_n = \alpha_n$

Remark:

A set of function which has the property that if  $\varphi_1, \varphi_2$  belongs to the set and  $c_1, c_2$  are any two constant then,

$c_1 \varphi_1 + c_2 \varphi_2$  belongs to the set also is called a linear space of functions.

We have seen that the set of all soln of  $L(y) = 0$  on an interval  $I$  is a linear of soln.

If a linear space of fun contains  $n$  functions  $\varphi_1, \varphi_2, \dots, \varphi_n$  which are linearly independent and such that every function in the space can be represented as a linear combinations of these then,

$\varphi_1, \varphi_2, \dots, \varphi_n$  is called a basis for the linear space and the dimension of the linear space the integer  $n$ .

Thm (5) tells that the functions  $\varphi_1, \varphi_2, \dots, \varphi_n$  satisfying the initial condition

$\varphi_i^{(j-1)} = 1, \varphi_i^{(j-1)} = 0 \quad j \neq i$

form a basis for the soln of  $L(y) = 0$  on  $I$  and this linear space of fun has dimension  $n$

1.a) Consider the eqn  $y'' + \frac{1}{x} y' - \frac{1}{x^2} y = 0$  for  $x > 0$

- (i) Show that there is a solution of the form  $x^r$  where  $r$  is a constant.  
(ii) Find two L.I. solutions for  $x > 0$ . P.T. they are L.I.  
(iii) Find the two solutions  $\phi_1, \phi_2$  satisfying

$$\phi_1(1) = 1, \quad \phi_2(1) = 0$$

$$\phi_1'(1) = 0, \quad \phi_2'(1) = 1$$

Soln:

Given eqn is  $y'' + \frac{1}{x} y' - \frac{1}{x^2} y = 0$

$$x^2 y'' + x y' - y = 0 \rightarrow \textcircled{1}$$

Let  $\phi(x) = x^r$  be a solution of this eqn.

$$\Rightarrow \phi'(x) = r x^{r-1}$$

$$\phi''(x) = r(r-1)x^{r-2}$$

$$\textcircled{1} \Rightarrow x^2 \phi'' + x \phi' - \phi = 0 \quad (\because \phi \text{ is soln})$$

$$x^2 r(r-1)x^{r-2} + x r x^{r-1} - x^r = 0$$

$$x^r r(r-1) + x^r r - x^r = 0$$

$$x^r (r^2 - r + r - 1) = 0$$

$$r^2 - 1 = 0$$

$$x^r \neq 0$$

$$r = \pm 1$$

$\therefore \phi_1(x) = x$  and  $\phi_2(x) = x^{-1} = \frac{1}{x}$  are two solutions.

$$\omega(\phi_1, \phi_2) = \begin{vmatrix} \phi_1 & \phi_2 \\ \phi_1' & \phi_2' \end{vmatrix} = \begin{vmatrix} x & \frac{1}{x} \\ 1 & -\frac{1}{x^2} \end{vmatrix}$$

$$= x \left( -\frac{1}{x^2} \right) - \frac{1}{x} = -\frac{2}{x} \neq 0$$

$$\therefore \omega(\phi_1, \phi_2) \neq 0$$

$\therefore$  The two solutions are linearly independent.

$\therefore \phi(x) = c_1 x + c_2 \frac{1}{x}$ ,  $c_1, c_2$  any constants is a solution of the eqn.

Given  $\phi_1(1) = 1$

$$\phi_1(1) = c_1 + c_2$$

$$c_1 + c_2 = 1 \rightarrow \textcircled{2}$$

$$\phi_1'(x) = c_1 - c_2 \frac{1}{x^2} \quad \text{Given } \phi_1'(1) = 0$$

$$\phi_1'(1) = c_1 - c_2$$

$$c_1 - c_2 = 0 \rightarrow \textcircled{3}$$

$$\textcircled{2} \Rightarrow c_1 + c_2 = 1$$

$$\textcircled{3} \Rightarrow c_1 - c_2 = 0$$

$$2c_1 = 1$$

$$c_1 = \frac{1}{2}$$

$$\Rightarrow c_2 = \frac{1}{2}$$

$$\therefore \phi_1(x) = \frac{1}{2}x + \frac{1}{2} \cdot \frac{1}{x^2} \Rightarrow \frac{1}{2}(x + \frac{1}{x^2})$$

$$\text{Given } \phi_2(1) = 0$$

$$\phi_2(x) = c_1 x + c_2 \frac{1}{x}$$

$$\phi_2(1) = c_1 + c_2$$

$$c_1 + c_2 = 0 \rightarrow \textcircled{4}$$

$$\phi_2'(x) = c_1 - \frac{c_2}{x^2}$$

$$\text{Given } \phi_2'(1) = 1$$

$$\phi_2'(1) = c_1 - c_2$$

$$c_1 - c_2 = 1 \rightarrow \textcircled{5}$$

$$\textcircled{4} \Rightarrow c_1 + c_2 = 0$$

$$\textcircled{5} \Rightarrow c_1 - c_2 = 1$$

$$2c_1 = 1$$

$$c_1 = \frac{1}{2}$$

$$\Rightarrow c_2 = -\frac{1}{2}$$

$$\therefore \phi_2(x) = \frac{1}{2}x - \frac{1}{2} \cdot \frac{1}{x} \Rightarrow \frac{1}{2}(x - \frac{1}{x})$$

b) The eqn  $y' + a(x)y = 0$  has for a soln  $\phi(x) = \exp[-\int a(x)dx]$ ,

Here  $a(x)$  be continuous on an interval  $I$  containing  $x_0$ .

This suggest trying to find a soln of  $\mathcal{L}(y) = y'' + a(x)y' + b(x)y = 0$

of the form,  $\phi(x) = \exp[\int_{x_0}^x p(t) dt]$ , where  $p$  is a function,

to determined. s.t  $\phi$  is a soln of  $\mathcal{L}(y) = 0$  iff  $p$  satisfies

The first order non-linear eqn  $y' = -y^2 - a_1(x)y - a_2(x)$

This eqn is called Riccati eqn

Soln:

Given  $\varphi(x) = \exp \left[ \int_{x_0}^x p(t) dt \right]$

$$\varphi'(x) = \exp \left[ \int_{x_0}^x p(t) dt \right] p(x)$$

$$\varphi'(x) = \varphi(x) \cdot p(x)$$

$$(i) \varphi' = \varphi p$$

$$\varphi'' = \varphi' p + p' \varphi = \varphi p \cdot p + \varphi' p$$

$$\varphi'' = \varphi p^2 + p' \varphi$$

$\varphi$  is a soln of  $y' = 0$  iff  $\varphi'' + a_1(x)\varphi' + a_2(x)\varphi = 0$

$$(ii) \text{ iff } \Leftrightarrow (\varphi p^2 + p' \varphi) + a_1(x) \varphi p + a_2(x) \varphi = 0$$

$$\Leftrightarrow \varphi (p^2 + p' + a_1(x)p + a_2(x)) = 0$$

$$\Leftrightarrow p^2 + p' + a_1(x)p + a_2(x) = 0$$

$$\Leftrightarrow p' = -p^2 - a_1(x)p - a_2(x)$$

$\Rightarrow p$  satisfies the first order non-linear eqn.

$$y' = -y^2 - a_1(x)y - a_2(x)$$

1.c) Let  $\varphi_1, \varphi_2, \dots, \varphi_n$  be  $n$  continuous function on interval  $a \leq x \leq b$

Let  $\alpha_{ij} = \int_a^b \varphi_i(x) \varphi_j(x) dx$  ( $i, j = 1, 2, \dots, n$ ) and let  $\Delta$  denote the

determinant 
$$\Delta = \begin{vmatrix} \alpha_{11} & \alpha_{12} & \dots & \alpha_{1n} \\ \alpha_{21} & \alpha_{22} & \dots & \alpha_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{n1} & \alpha_{n2} & \dots & \alpha_{nn} \end{vmatrix}$$

P.T  $\varphi_1, \varphi_2, \dots, \varphi_n$  are linearly independent on  $a \leq x \leq b$  iff  $\Delta \neq 0$

Soln:

Suppose  $\Delta \neq 0$  and consider,

$$c_1 \varphi_1 + c_2 \varphi_2 + \dots + c_n \varphi_n = 0 \quad \text{--- (1)}$$

Multiplying (1) by  $\varphi_i$  throughout and integrating from  $a$  to  $b$  we get

$$c_1 \int_a^b \varphi_1 \varphi_1 dx + c_2 \int_a^b \varphi_1 \varphi_2 dx + \dots + c_n \int_a^b \varphi_1 \varphi_n dx = 0$$

$$(ii) c_1 \alpha_{11} + c_2 \alpha_{12} + \dots + c_n \alpha_{1n} = 0$$

Similarly multiplying ① term by  $\bar{\varphi}_2, \dots, \bar{\varphi}_n$  and integrating from  $a$  to  $b$ . (49)

(13)

$$C_1 \alpha_{21} + C_2 \alpha_{22} + \dots + C_n \alpha_{2n} = 0$$

$\vdots$

$$C_1 \alpha_{n1} + C_2 \alpha_{n2} + \dots + C_n \alpha_{nn} = 0$$

But the determinant of the coefficients of above system of eqn is just  $\Delta$  which is not zero.

$\therefore$  The only soln of the system is

$$C_1 = C_2 = \dots = C_n = 0$$

$\therefore \varphi_1, \varphi_2, \dots, \varphi_n$  are linearly independent.

Conversely if,

$\varphi_1, \varphi_2, \dots, \varphi_n$  are linearly independent and if possible  $\Delta = 0$

Then there are constants  $C_1, C_2, \dots, C_n$  not all zero such that,

$$C_1 \alpha_{11} + C_2 \alpha_{12} + \dots + C_n \alpha_{1n} = 0$$

$$C_1 \alpha_{21} + C_2 \alpha_{22} + \dots + C_n \alpha_{2n} = 0$$

$\vdots$

$$C_1 \alpha_{n1} + C_2 \alpha_{n2} + \dots + C_n \alpha_{nn} = 0$$

Multiplying ① by  $\bar{\varphi}_1$ , the second by  $\bar{\varphi}_2$ , and so on and adding all the equations we get,

$$\sum_{j=1}^n \sum_{i=1}^n \bar{\varphi}_i \alpha_{ij} C_j = 0$$

$$\Leftrightarrow \int_a^b \left| \sum_{i=1}^n C_i \varphi_i(x) \right|^2 dx = 0$$

$$\Rightarrow \sum_{i=1}^n C_i \varphi_i(x) = 0$$

$$\Leftrightarrow C_1 \varphi_1 + C_2 \varphi_2 + \dots + C_n \varphi_n = 0$$

This shows that  $\varphi_1, \varphi_2, \dots, \varphi_n$  are linearly dependent.

a contradiction  $\Delta \neq 0$ .

1.d) Method of removal of first derivative.

Consider the eqn  $L(y) = y'' + a_1(x)y' + a_2(x)y = 0$ , where  $a_1, a_2$  are continuous on some interval  $I$  and  $a_1$  has a continuous derivative there.

a) If  $\psi$  is a soln of  $L(y) = 0$ . Let  $\phi = u\psi$  and determine a differential eqn for  $u$  which will make  $\psi$  the soln of an eqn in which the first derivative term is absent.

b) Solve this differential eqn for  $u$ .

c) s.t  $\psi$  will then satisfy the eqn  $y'' + \alpha(x)y = 0$

where  $\alpha = a_2 - \frac{a_1^2}{4} - \frac{a_1'}{2}$

Soln:

Let  $\phi = u\psi$

Since  $L(\phi) = 0$  we get,  $L(u\psi) = 0$

i)  $L(u\psi)'' + a_1(u\psi)' + a_2 u\psi = 0$

$u\psi'' + 2u'\psi' + u''\psi + a_1(u\psi)' + a_2 u\psi = 0$

$u\psi'' + \psi'(2u' + a_1u) + \psi(u'' + a_1u' + a_2u) = 0 \rightarrow \textcircled{1}$

Since the first derivative term is to be absent.

$\therefore 2u' + a_1u = 0 \rightarrow \textcircled{2}$

This is linear in  $u$

A soln of this eqn is

$u = c e^{-\frac{1}{2} \int a_1(x) dx}$

$c$  being any constant,

$\textcircled{1} \Rightarrow u\psi'' + \psi(u'' + a_1u' + a_2u) = 0$

$\textcircled{2} \Rightarrow u' = c e^{-\frac{1}{2} \int a_1(x) dx} (-\frac{1}{2} a_1)$

$u'' = -\frac{1}{2} a_1 u'$

$u'' = -\frac{1}{2} [a_1 u' + a_1' u]$

$\therefore u'' + a_1 u' + a_2 u = -\frac{1}{2} [a_1 u' + a_1' u] + a_1 u' + a_2 u$

$= \frac{a_1 u'}{2} - \frac{a_1' u}{2} + a_2 u$

1.d) Method of removal of first derivative.

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b) Solve this differential eqn for  $u$ .

c) s.t  $\psi$  will then satisfy the eqn  $y'' + \alpha(x)y = 0$

where  $\alpha = a_2 - \frac{a_1^2}{4} - \frac{a_1'}{2}$

Soln:

Let  $\phi = u\psi$

Since  $L(\phi) = 0$  we get,  $L(u\psi) = 0$

i)  $L(u\psi)'' + a_1(u\psi)' + a_2 u\psi = 0$

$u\psi'' + 2u'\psi' + u''\psi + a_1(u\psi)' + a_2 u\psi = 0$

$u\psi'' + \psi'(2u' + a_1 u) + \psi(u'' + a_1 u' + a_2 u) = 0 \rightarrow \textcircled{1}$

Since the first derivative term is to absent.

$\therefore 2u' + a_1 u = 0 \rightarrow \textcircled{2}$

This is linear in  $u$

A soln of this eqn is

$u = c e^{-\frac{1}{2} \int a_1(x) dx} \rightarrow \textcircled{3}$

$c$  being any constant,

$\textcircled{1} \Rightarrow u\psi'' + \psi(u'' + a_1 u' + a_2 u) = 0$

$\textcircled{2} \Rightarrow u' = c e^{-\frac{1}{2} \int a_1(x) dx} \left(-\frac{1}{2} a_1\right)$

$u'' = -\frac{1}{2} a_1 u'$

$u'' = -\frac{1}{2} [a_1 u' + a_1' u]$

$\therefore u'' + a_1 u' + a_2 u = -\frac{1}{2} [a_1 u' + a_1' u] + a_1 u' + a_2 u$

$= \frac{a_1 u'}{2} - \frac{a_1' u}{2} + a_2 u$

$$= \frac{a_2}{2} (-\frac{1}{2} a_1 u) - \frac{a_1'}{2} u + a_3 u$$

(51)

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$$= (-\frac{a_1^2}{4} - \frac{a_1'}{2} + a_3) u$$

Sub in (1) we get,

$$u u'' + u u' [a_3 - \frac{a_1^2}{2} - \frac{a_1'}{4}] = 0$$

(i)  $u'' + \alpha u = 0$ , where  $\alpha = a_3 - \frac{a_1^2}{2} - \frac{a_1'}{4}$

Section-4

The Wronskian and linear independence.

In order to show that any set of  $n$  linearly independent solns of  $L(y) = 0$  can serve as a basis for the solns of  $L(y) = 0$ . We consider the Wronskian  $w(\phi_1, \phi_2, \dots, \phi_n)$  of any  $n$  solns  $\phi_1, \phi_2, \dots, \phi_n$ . The determinant is defined as,

$$w(\phi_1, \phi_2, \dots, \phi_n) = \begin{vmatrix} \phi_1 & \phi_2 & \dots & \phi_n \\ \phi_1' & \phi_2' & \dots & \phi_n' \\ \vdots & \vdots & \dots & \vdots \\ \phi_1^{(n-1)} & \phi_2^{(n-1)} & \dots & \phi_n^{(n-1)} \end{vmatrix}$$

Theorem: 6

If  $\phi_1, \phi_2, \dots, \phi_n$  are  $n$  solns of  $L(y) = 0$  on an interval  $I$  on an interval  $I$  they are linearly independent iff  $w(\phi_1, \phi_2, \dots, \phi_n)(x) \neq 0 \forall x$  in  $I$

Proof:

First suppose  $w(\phi_1, \phi_2, \dots, \phi_n)(x) \neq 0 \forall x$  in  $I$ .

If there are constants  $c_1, c_2, \dots, c_n$  such that,

$$c_1 \phi_1(x) + c_2 \phi_2(x) + \dots + c_n \phi_n(x) = 0 \rightarrow (1)$$

Then clearly,

$$\begin{aligned} c_1 \phi_1'(x) + c_2 \phi_2'(x) + \dots + c_n \phi_n'(x) &= 0 \\ \vdots \\ c_1 \phi_1^{(n-1)}(x) + c_2 \phi_2^{(n-1)}(x) + \dots + c_n \phi_n^{(n-1)}(x) &= 0 \end{aligned} \rightarrow (2)$$

for fixed  $x$  in  $I$  The eqn (1) and (2) are  $n$  linear homogeneous equations satisfied by  $c_1, c_2, \dots, c_n$ . The determinant of the coefficient is  $w(\phi_1, \phi_2, \dots, \phi_n)(x)$ , which is not zero

Hence there is only one soln to this system which is

$$c_1 = c_2 = \dots = c_n = 0$$

$\therefore \phi_1, \phi_2, \dots, \phi_n$  are linearly independent on  $I$ .

conversely,

suppose  $\phi_1, \phi_2, \dots, \phi_n$  are linearly independent on  $I$ .

suppose there is an  $x_0$  in  $I$  s.t.

$$\omega(\phi_1, \phi_2, \dots, \phi_n)(x_0) = 0.$$

$\rightarrow$  The system of  $n$  linear equations

$$c_1 \phi_1(x_0) + c_2 \phi_2(x_0) + \dots + c_n \phi_n(x_0) = 0.$$

$$c_1 \phi_1'(x_0) + c_2 \phi_2'(x_0) + \dots + c_n \phi_n'(x_0) = 0.$$

$$\vdots$$
$$c_1 \phi_1^{(n-1)}(x_0) + c_2 \phi_2^{(n-1)}(x_0) + \dots + c_n \phi_n^{(n-1)}(x_0) = 0$$

$\rightarrow$  ③

has a soln  $c_1, c_2, \dots, c_n$  where not all the constants  $c_1, c_2, \dots, c_n$  are zero.

Let  $c_1, c_2, \dots, c_n$  be such a soln and let us consider the function.

$$\psi = c_1 \phi_1 + c_2 \phi_2 + \dots + c_n \phi_n$$

Now  $L(\psi) = 0$  and from ③ we see that,

$$\psi(x_0) = 0, \quad \psi'(x_0) = 0, \quad \dots, \quad \psi^{(n-1)}(x_0) = 0$$

$\therefore$  from uniqueness thm it follows that

$$\psi(x) = 0 \quad \forall x \text{ in } I$$

and hence,

$$c_1 \phi_1(x) + c_2 \phi_2(x) + \dots + c_n \phi_n(x) = 0, \quad \forall x \text{ in } I$$

But this contradicts the fact that  $\phi_1, \phi_2, \dots, \phi_n$  are L.I. on  $I$ .

Thus our assumption that there is a point  $x_0$  in  $I$  s.t.

$$\omega(\phi_1, \phi_2, \dots, \phi_n)(x_0) = 0 \text{ must be false.}$$

$\therefore$  Hence  $\omega(\phi_1, \phi_2, \dots, \phi_n)(x) \neq 0, \quad \forall x \text{ in } I$ .

Theorem: 7

Let  $\phi_1, \phi_2, \dots, \phi_n$  be  $n$  linearly independent solns of  $L(y) = 0$  on an interval  $I$ . If  $\psi$  is any soln of  $L(y) = 0$  on  $I$  it can be represented in the form,  $\psi = c_1 \phi_1 + c_2 \phi_2 + \dots + c_n \phi_n$ .

where  $c_1, c_2, \dots, c_n$  are constants. Thus any set of  $n$  linearly independent solns of  $L(y) = 0$  on  $I$  is a basis for the solns of  $L(y) = 0$  on  $I$ .

Proof:

Let  $x_0$  be a point in  $I$  and

Suppose  $\psi(x_0) = d_1, \psi'(x_0) = d_2, \dots, \psi^{(n-1)}(x_0) = d_n$

we show that there exist unique constants  $c_1, c_2, \dots, c_n \in \mathbb{R}$

$\psi = c_1 \phi_1 + c_2 \phi_2 + \dots + c_n \phi_n$  is a soln of  $L(y) = 0$  satisfying

$\psi(x_0) = d_1, \psi'(x_0) = d_2, \dots, \psi^{(n-1)}(x_0) = d_n$ .

By uniqueness thm, we have,

$\psi = \psi$  (or)

$\psi = c_1 \phi_1 + c_2 \phi_2 + \dots + c_n \phi_n$

The initial conditions for  $\psi$  are equivalent to the following equations for  $c_1, c_2, \dots, c_n$ .

$$\begin{aligned} c_1 \phi_1(x) + c_2 \phi_2(x) + \dots + c_n \phi_n(x) &= d_1 \\ c_1 \phi_1'(x) + c_2 \phi_2'(x) + \dots + c_n \phi_n'(x) &= d_2 \\ \vdots & \\ c_1 \phi_1^{(n-1)}(x) + c_2 \phi_2^{(n-1)}(x) + \dots + c_n \phi_n^{(n-1)}(x) &= d_n \end{aligned} \quad \rightarrow \textcircled{1}$$

This is a set of linear eqn for  $c_1, c_2, \dots, c_n$ .

The determinant of the coefficient is  $w(\phi_1, \phi_2, \dots, \phi_n)(x_0)$  which is not zero.

Since  $\phi_1, \phi_2, \dots, \phi_n$  are l.i (by above theorem).

$\therefore$  There is unique soln  $c_1, c_2, \dots, c_n$  of  $\textcircled{1}$

Hence the theorem.